

# Previous lecture

Consider

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & Ax = b \\ & x \geq 0. \end{aligned} \quad (P)$$

Given a basis  $B$ , (P) is equivalent to

$$\begin{aligned} \min \quad & \bar{c}^T x \\ \text{s.t.} \quad & \bar{A} x = \bar{b} \\ & x \geq 0, \end{aligned} \quad (\text{tableau})$$

where

$$B = A_B$$

$$\bar{c}^T = c^T - c_B^T B^{-1} A$$

$$\bar{A} = B^{-1} A$$

$$\bar{b} = B^{-1} b$$

properties of tableau:

$$\bar{c}^T = \left[ \begin{array}{c|c} 0^T & \bar{c}_N^T \end{array} \right]$$

$$\bar{A} = \left[ \begin{array}{c|c} \mathbf{I} & \bar{A}_N \end{array} \right]$$

$\beta$

corresponding basic solution:

$$x_N = 0 \quad \text{so} \quad \bar{A}x = \left[ \begin{array}{c|c} \mathbf{I} & \bar{A}_N \end{array} \right] \begin{bmatrix} x_\beta \\ x_N \end{bmatrix} = \bar{b}$$

$\uparrow$

yields  $\mathbf{I}x_\beta = \bar{b}$

i.e.,  $x = \left[ \begin{array}{c} \bar{b} \\ 0 \end{array} \right] \} \beta$

note: basic <sup>feasible</sup> solutions  $\Leftrightarrow$  vertices of (P)

We want to go from a feasible basis to a better feasible basis (without enumerating all bases)

Def. Let  $l \in \mathcal{B}$ ,  $e \in \mathcal{N}$ .

A pivot is the action of creating

$$\mathcal{B}' = \mathcal{B} \setminus \{l\} \cup \{e\}.$$

$x_e$  is the entering variable.

$x_l$  is the leaving variable.

If we pivot away from current basis,

- one nonbasic variable,  $x_e$  (currently = 0) will become basic (hence  $\geq 0$ ).
- the value of the basic variables will change to preserve feasibility ( $\geq 0$ ).
- how will the objective value change?
  - $\forall j \in \mathcal{B}$ ,  $\bar{c}_j = 0$  so  $x_j$  has no impact
  - $\forall j \in \mathcal{N} \setminus \{e\}$ ,  $\bar{x}_j = 0$  and stays zero  $\rightarrow$  no impact
  - $x_e$  can increase, so objective can decrease if  $\bar{c}_e < 0$

# Example tableau

min

$$\begin{array}{rcccccc} & & & 3x_4 & -2x_5 & & \\ & x_1 & & +2x_4 & -x_5 & = & 2 \\ & & x_2 & -x_4 & +x_5 & = & 1 \\ & & & & +2x_5 & = & 1 \\ & x_1, & x_2, & x_3, & x_4, & x_5 & \geq 0 \end{array}$$

basic solution :  $\bar{x} = (2, 1, 1, 0, 0)$

In the example,

$x_5$  enters the basis  $\Rightarrow$

(all other nonbasics, i.e.  $x_4$ , are fixed to 0)

$$x_1 = 2 + x_5 \geq 0$$

$$x_2 = 1 - x_5 \geq 0 \rightarrow x_5 \leq 1$$

$$x_3 = 1 - 2x_5 \geq 0 \rightarrow 2x_5 \leq 1$$

$\Rightarrow x_5$  will increase to  $\frac{1}{2}$

$x_3$  become zero, can leave  
the basis

When  $x_e$  increases:

if  $\bar{a}_{ie} \leq 0$ ,  $x_j$  increases or stays unchanged

if  $\bar{a}_{ie} > 0$ ,  $x_j$  decreases:

when  $x_e$  reaches  $\frac{\bar{b}_i}{\bar{a}_{ie}}$ ,  $x_j$  reaches 0

⇒ Ratio test:

by how much can  $x_e$  increase?

$$\lambda = \min_i \left\{ \frac{\bar{b}_i}{\bar{a}_{ie}} \mid \bar{a}_{ie} > 0 \right\}$$

Leaving variable: any  $i$ -th basic variable such that  $\bar{a}_{ie} > 0$  and  $\lambda = \frac{\bar{b}_i}{\bar{a}_{ie}}$ .

More formally,

Let  $x_e$  enter the basis (with  $\bar{c}_e < 0$ ).

Consider  $x_j$  where  $j \in \mathcal{B}$ ,  $j$  is the  $i$ -th basic variable.

$$x_j + \overbrace{\dots}^0 + \bar{a}_{ie} x_e = \bar{b}_i$$

So  $x_j = \bar{b}_i - \bar{a}_{ie} \cdot x_e$



# Simplex method

- Given a basis  $\mathcal{B}$  such that  $\bar{b} \geq 0$ ,
- choose entering variable  $x_e$ :  $\bar{z}_e < 0$
  - choose pivot row  
$$i = \operatorname{argmin}_i \left\{ \frac{\bar{b}_i}{\bar{a}_{ie}} \mid \bar{a}_{ie} > 0 \right\}$$
  - leaving variable  $x_\ell$  is the basic variable in row  $i$ .
  - pivot ( $x_e$  enters,  $x_\ell$  leaves)

The algorithm ends when

- there is no entering variable (optimality)
- there is no leaving variable (unboundedness)

# DUALITY

Consider 
$$z = \max 2x_1 + x_2$$
$$\text{s.t. } \begin{aligned} x_1 + 2x_2 &\leq 2 \\ x_1 + x_2 &\leq 2 \\ x_1 - x_2 &\leq 0.5 \end{aligned}$$
 (P)

Consider  $\bar{x} = (1, 0.5)$ ,  $\bar{z} = 2.5$

Q: Is  $\bar{x}$  optimal?

A: It is optimal if  $2x_1 + x_2 \leq 2.5 \forall x$  feasible

Q: Could we show  $2x_1 + x_2 \leq U$  for some  $U$

A: Take linear combinations of constraints  
 $\downarrow$  (with  $\geq 0$  coefficients)

$$x_1 + 2x_2 \leq 2$$

$$(x \ 1/3)$$

$$x_1 + x_2 \leq 2$$

$$(x \ 1)$$

$$x_1 - x_2 \leq 0.5$$

$$(x \ 2/3)$$

---

$$2x_1 + x_2 \leq 3$$

(still not sure  $\bar{x}$  is optimal)

General approach:

$$x_1 + 2x_2 \leq 2 \quad (x, y_1)$$

$$x_1 + x_2 \leq 2 \quad (x, y_2)$$

$$x_1 - x_2 \leq 0.5 \quad (x, y_3)$$

---

$$(y_1 + y_2 + y_3) x_1 + (2y_1 + y_2 - y_3) x_2 \leq 2y_1 + 2y_2 + 0.5y_3$$

We want:

$$2x_1 + x_2 \leq 2y_1 + 2y_2 + 0.5y_3$$

It will work as long as:

$$y_1 + y_2 + y_3 = 2$$

$$2y_1 + y_2 - y_3 = 1$$

$$y_1, y_2, y_3 \geq 0$$

in which case it gives  $U = 2y_1 + 2y_2 + 0.5y_3$

We want the strongest possible upper bound  $U$ .

$$\begin{aligned} U = \min \quad & 2y_1 + 2y_2 + 0.5y_3 \\ & y_1 + y_2 + y_3 = 2 \\ & 2y_1 + y_2 - y_3 = 1 \\ & y_1, y_2, y_3 \geq 0 \end{aligned} \quad (D)$$

(D) is the dual of (P)

Note:  $y^* = (1, 0, 1)$  feasible for (D)

gives  $U = 2.5 \Rightarrow \bar{x}$  optimal for (P)