

Previous lecture

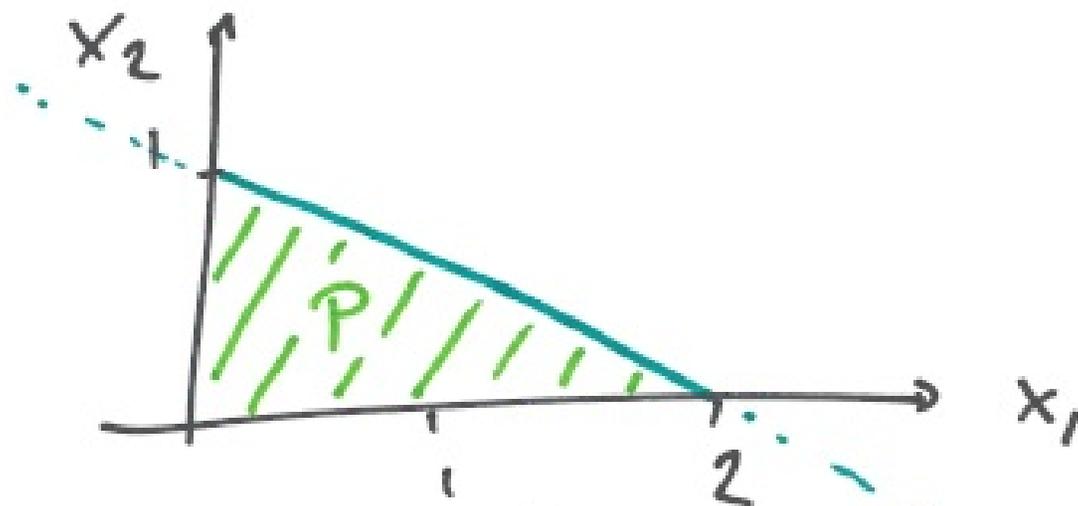
$$A \in \mathbb{Z}^{m \times n} \text{ is TU, } b \in \mathbb{Z}^m$$

$\Rightarrow \{x \in \mathbb{R}^n : Ax \leq b\}$ has
integer vertices

Remark: (\Rightarrow) sufficient but not necessary ~~(\Leftarrow)~~

For example, take

$$P = \left\{ x \in \mathbb{R}^2 : \begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 0 & -1 \end{bmatrix} x \leq \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} \right\}$$



P has integral vertices $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

However $\begin{bmatrix} 1 & 2 \\ -1 & 0 \\ 0 & -1 \end{bmatrix}$ is not TU.

Constructing TU matrices

Theorem 7. Let $A \in \mathbb{Z}^{m \times n}$ be a $-1, 0, +1$ matrix in which each column has

- at most one $+1$ entry, and
- at most one -1 entry.

Then A is TU.

Example

$$\left[\begin{array}{c|c|c|c|c} \textcircled{-1} & 0 & 0 & \textcircled{-1} & 0 \\ \textcircled{+1} & \textcircled{-1} & 0 & 0 & 0 \\ 0 & 0 & \textcircled{+1} & 0 & 0 \\ 0 & \textcircled{+1} & 0 & \textcircled{+1} & 0 \end{array} \right]$$

Remark: (\Rightarrow) sufficient but not necessary ~~(\Leftarrow)~~

For example: $\left[\begin{array}{c|c} +1 & +1 \\ +1 & 0 \end{array} \right]$ is TU.

proof of Theorem 7:

We will show that every $k \times k$ submatrix M of A has $\det(M) \in \{-1, 0, +1\}$.

We proceed by induction on k .

Base case: $k=1$: true since entries are $-1, 0, +1$.

Suppose $k \geq 2$, and result holds for $k-1$.

Case 1: M has an all-zero column.

$$M = \left[\begin{array}{c|c} 0 & ? \end{array} \right], \det(M) = 0 \text{ done.}$$

Case 2: every column has one $+1$ and one -1 .

Let us sum all rows:

$$\begin{bmatrix} 1 & 1 & \dots & 1 \end{bmatrix} \cdot \begin{bmatrix} +1 & -1 & +1 & -1 \\ -1 & +1 & -1 & +1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & \dots & 0 \end{bmatrix}$$

$$M^T \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ 0 \end{bmatrix}$$

$\Rightarrow M^T$ not invertible

$\Rightarrow \det(M^T) = \det(M) = 0$ done.

Case 3: There is a column of M with exactly one $+1$ or one -1 .

$$M = \begin{bmatrix} e_i & | & G \end{bmatrix} \text{ or } M = \begin{bmatrix} -e_i & | & G \end{bmatrix}$$

G is $k \times (k-1)$, so every square submatrix H of G is $(k-1) \times (k-1)$ at most.

So by induction hypothesis,
H is unimodular (i.e. $\det(H) \in \{-1, 0, +1\}$)
By definition, this means G is TU.
By Theorem 5(d), M is TU.
In particular, $\det(M) \in \{-1, 0, +1\}$.
→ done.

Remark: M is TU \Leftrightarrow M^T is TU,
so Theorem 7 applies to rows
as well.

Application to flows

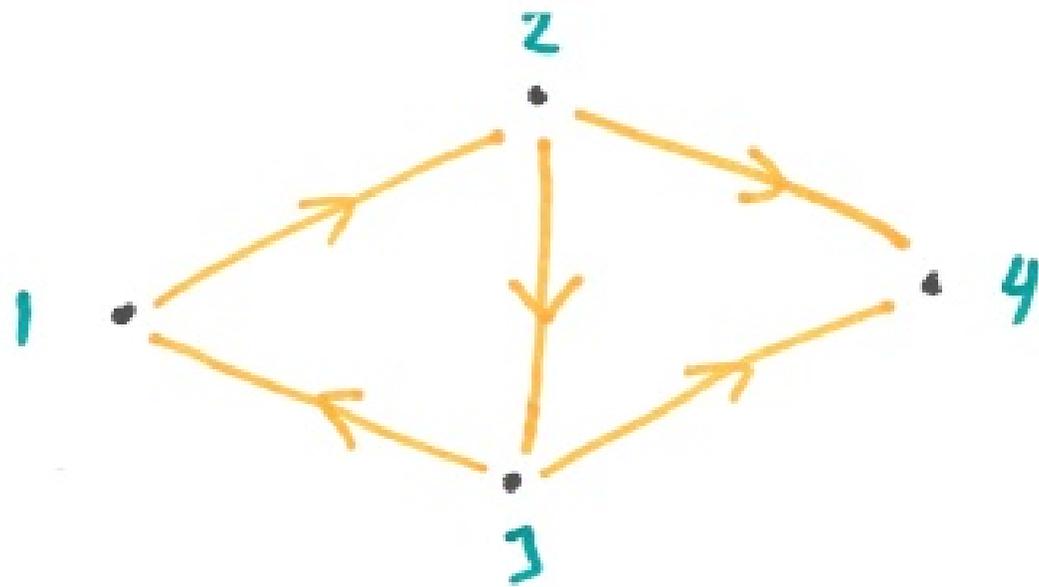
Let $G=(V, E)$ be a directed graph.

Definition The vertex-arc incidence matrix of G has rows indexed by V and columns indexed by E .

For every column/edge uv , we have

- +1 in row u ,
- 1 in row v ,
- 0 everywhere else

Example:



$$M = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} +1 & -1 & & & & \\ -1 & & +1 & +1 & & \\ & +1 & -1 & & & +1 \\ & & & -1 & & -1 \end{bmatrix} \end{matrix}$$

$12 \quad 31 \quad 23 \quad 24 \quad 34$

Remark: For every row/vertex v , we have

- +1 in every column e if $e \in \delta^+(v)$
- 1 in every column e if $e \in \delta^-(v)$
- 0 otherwise

Therefore, a min-cost flow formulation for G

$$\begin{aligned} \max \quad & c^T x \\ & f_q(x) = b_q, \quad \forall q \in V \\ & 0 \leq x \leq u \end{aligned}$$

where $f_x(q) = \sum_{e \in \delta^+(q)} x_e - \sum_{e \in \delta^-(q)} x_e,$

can be rewritten

$$\max c^T x$$

$$Mx = b$$

$$0 \leq x \leq u.$$

In the example:

$$\begin{bmatrix} +1 & -1 & & & \\ \hline -1 & & +1 & +1 & \\ \hline & +1 & -1 & & +1 \\ \hline & & & -1 & -1 \end{bmatrix} \times = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

12 31 23 24 34

Theorem 8

Consider the min-cost flow

formulation

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & f_x(q) = b_q, \quad \forall q \in V \\ & 0 \leq x \leq u \end{aligned} \quad (P)$$

where $b \in \mathbb{Z}^{|V|}$, $u \in \mathbb{Z}^{|E|}$.

If (P) has an optimal solution, then it has an integral optimal solution.

proof Observe that (P) is equivalent to

$$\begin{array}{l} \text{min} \\ \text{s.t.} \end{array} \quad C^T x$$
$$\begin{bmatrix} M \\ -M \\ I \\ -I \end{bmatrix} x \leq \begin{bmatrix} b \\ -b \\ u \\ 0 \end{bmatrix}$$

where M is the vertex-arc incidence matrix of G .

By Theorem 7, M is TU.

By Theorem 5 (and its Corollary), $\begin{bmatrix} M \\ -M \\ I \\ -I \end{bmatrix}$ is TU.

By Theorem 6, the vertices of the feasible region of (P) are integral.

Since (P) is an LP, if it has an optimal solution, at least one is a vertex.

Theorem 9: Consider the max-flow problem

$$(P) \quad \begin{array}{l} \max \quad f_x(s) \\ \text{s.t.} \quad f_x(q) = 0 \quad \forall q \in V \setminus \{s, t\} \\ 0 \leq x \leq u. \end{array}$$

If (P) has an optimal solution, then at least one is integral.

proof: Same as Theorem 8.